

PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

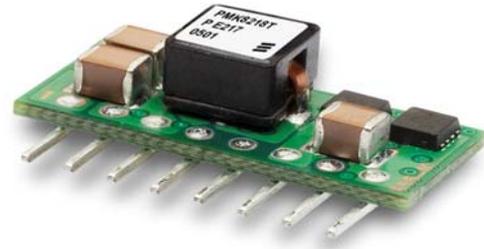
**Key Features**

- 8A output current
- 12V input voltage
- Output voltages from (0.8V up to 1.8V)/(1.2V up to 5.5V)
- Industry standard POLA™ compatible
- 22.86 x 10.15 x 6.86 mm (0.900 x 0.400 x 0.270 in.)
- High efficiency, up to. 93%
- Auto Track™ sequencing pin
- More than 5 million hours MTBF



**General Characteristics**

- Operating temperature: -40°C to 85 °C
- Output short-circuit protection
- Over temperature protection
- On/Off inhibit control
- Highly automated manufacturing ensures quality
- ISO 9001/14001 certified supplier



**Safety Approvals**



Pending

**Design for Environment**



Meets requirements in high-temperature lead-free soldering processes.

**Contents**

General Information	2
Safety Specification	3
Absolute Maximum Ratings	4
Product Program	Ordering No.
1.8 V/8 A	PMK 8118T
0.8 V/8 A Electrical Specification	6
1.0 V/8 A Electrical Specification	7
1.2 V/8 A Electrical Specification	8
1.5 V/8 A Electrical Specification	9
1.8 V/8 A Electrical Specification	10
3.3 V/8 A	PMK 8418L
1.2 V/8 A Electrical Specification	12
1.5 V/8 A Electrical Specification	13
1.8 V/8 A Electrical Specification	14
2.5 V/8 A Electrical Specification	15
3.3 V/8 A Electrical Specification	16
5.0 V/8 A Electrical Specification	17
EMC Specification	18
Operating Information	18
Thermal Consideration	20
Connections	21
Mechanical Information	22
Soldering Information	23
Delivery Information	23
Product Qualification Specification	24

PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

**General Information**

**Ordering Information**

See Contents for individual product ordering numbers.

Option	Suffix	Ordering No.
Through hole pin	P	PMK 8418L P PMK 8118T P

**Reliability**

The Mean Time Between Failure (MTBF) is calculated at full output power and an operating ambient temperature ( $T_A$ ) of +40°C, which is a typical condition in Information and Communication Technology (ICT) equipment. Different methods could be used to calculate the predicted MTBF and failure rate which may give different results. Ericsson Power Modules currently uses Telcordia SR332.

Predicted MTBF for the series is:

- 5 million hours according to Telcordia SR332, issue 1, Black box technique.

Telcordia SR332 is a commonly used standard method intended for reliability calculations in ICT equipment. The parts count procedure used in this method was originally modelled on the methods from MIL-HDBK-217F, Reliability Predictions of Electronic Equipment. It assumes that no reliability data is available on the actual units and devices for which the predictions are to be made, i.e. all predictions are based on generic reliability parameters.

**Compatibility with RoHS requirements**

The products are compatible with the relevant clauses and requirements of the RoHS directive 2002/95/EC and have a maximum concentration value of 0.1% by weight in homogeneous materials for lead, mercury, hexavalent chromium, PBB and PBDE and of 0.01% by weight in homogeneous materials for cadmium.

Exemptions in the RoHS directive utilized in Ericsson Power Modules products include:

- Lead in high melting temperature type solder (used to solder the die in semiconductor packages)
- Lead in glass of electronics components and in electronic ceramic parts (e.g. fill material in chip resistors)
- Lead as an alloying element in copper alloy containing up to 4% lead by weight (used in connection pins made of Brass)

The exemption for lead in solder for servers, storage and storage array systems, network infrastructure equipment for switching, signaling, transmission as well as network management for telecommunication is only utilized in surface mount products intended for end-users' leaded SnPb Eutectic soldering processes.

**Quality Statement**

The products are designed and manufactured in an industrial environment where quality systems and methods like ISO 9000, 6σ (sigma), and SPC are intensively in use to boost the continuous improvements strategy. Infant mortality or early failures in the products are screened out and they are subjected to an ATE-based final test. Conservative design rules, design reviews and product qualifications, plus the high competence of an engaged work force, contribute to the high quality of our products.

**Warranty**

Warranty period and conditions are defined in Ericsson Power Modules General Terms and Conditions of Sale.

**Limitation of Liability**

Ericsson Power Modules does not make any other warranties, expressed or implied including any warranty of merchantability or fitness for a particular purpose (including, but not limited to, use in life support applications, where malfunctions of product can cause injury to a person's health or life).

PMK 8000 series POL regulator, Input 12 V, Output 8 A/44 W	EN/LZT 146 363 R1B Dec 2006 © Ericsson Power Modules AB
---	--

## Safety Specification

### General information

Ericsson Power Modules DC/DC converters and DC/DC regulators are designed in accordance with safety standards IEC/EN/UL60950, *Safety of Information Technology Equipment*.

IEC/EN/UL60950 contains requirements to prevent injury or damage due to the following hazards:

- Electrical shock
- Energy hazards
- Fire
- Mechanical and heat hazards
- Radiation hazards
- Chemical hazards

On-board DC-DC converters are defined as component power supplies. As components they cannot fully comply with the provisions of any Safety requirements without "Conditions of Acceptability". It is the responsibility of the installer to ensure that the final product housing these components complies with the requirements of all applicable Safety standards and Directives for the final product.

Component power supplies for general use should comply with the requirements in IEC60950, EN60950 and UL60950 "*Safety of information technology equipment*".

There are other more product related standards, e.g. IEEE802.3af "Ethernet LAN/MAN Data terminal equipment power", and ETS300132-2 "Power supply interface at the input to telecommunications equipment; part 2: DC", but all of these standards are based on IEC/EN/UL60950 with regards to safety.

Ericsson Power Modules DC/DC converters and DC/DC regulators are UL60950 recognized and certified in accordance with EN60950.

The flammability rating for all construction parts of the products meets requirements for V-0 class material according to IEC 60695-11-10.

The products should be installed in the end-use equipment, in accordance with the requirements of the ultimate application. Normally the output of the DC/DC converter is considered as SELV (Safety Extra Low Voltage) and the input source must be isolated by minimum Double or Reinforced Insulation from the primary circuit (AC mains) in accordance with IEC/EN/UL60950.

### Isolated DC/DC converters

It is recommended that a slow blow fuse with a rating twice the maximum input current per selected product be used at the input of each DC/DC converter. If an input filter is used in the circuit the fuse should be placed in front of the input filter.

In the rare event of a component problem in the input filter or in the DC/DC converter that imposes a short circuit on the input source, this fuse will provide the following functions:

- Isolate the faulty DC/DC converter from the input power source so as not to affect the operation of other parts of the system.
- Protect the distribution wiring from excessive current and power loss thus preventing hazardous overheating.

The galvanic isolation is verified in an electric strength test. The test voltage ( $V_{iso}$ ) between input and output is 1500 Vdc or 2250 Vdc for 60 seconds (refer to product specification).

Leakage current is less than 1  $\mu$ A at nominal input voltage.

### 24 V DC systems

The input voltage to the DC/DC converter is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

### 48 and 60 V DC systems

If the input voltage to Ericsson Power Modules DC/DC converter is 75 Vdc or less, then the output remains SELV (Safety Extra Low Voltage) under normal and abnormal operating conditions.

Single fault testing in the input power supply circuit should be performed with the DC/DC converter connected to demonstrate that the input voltage does not exceed 75 Vdc.

If the input power source circuit is a DC power system, the source may be treated as a TNV2 circuit and testing has demonstrated compliance with SELV limits and isolation requirements equivalent to Basic Insulation in accordance with IEC/EN/UL60950.

### Non-isolated DC/DC regulators

The input voltage to the DC/DC regulator is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.



PMK 8000 series POL regulator, Input 12 V, Output 8 A/44 W	EN/LZT 146 363 R1B Dec 2006
	© Ericsson Power Modules AB

**1.8 V/8 A Electrical Specification**
**PMK 8118T**
 $T_{ref} = -40$  to  $+85^{\circ}\text{C}$ ,  $V_I = 10.8$  to  $13.2$  V,  $R_{adj} = 130$   $\Omega$ , unless otherwise specified under Conditions.

 Typical values given at:  $T_{ref} = +25^{\circ}\text{C}$ ,  $V_I = 12$  V, max  $I_O$ , unless otherwise specified under Conditions.

 Additional  $C_{in1} = 100\mu\text{F}$ ;  $C_{in2} = 10\mu\text{F}$  and  $C_{out} = 100\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit
$V_I$	Input voltage range		10.8		13.2	V
UVLO	Undervoltage lockout	$V_I = \text{increasing}$		9.5	10.4	V
		$V_I = \text{decreasing}$	8.8	9		
$C_I$	Internal input capacitance			TBD		$\mu\text{F}$
$P_O$	Output power		0		14.4	W
$\eta$	Efficiency	50 % of max $I_O$		TBD		%
		max $I_O$		87		
$P_d$	Power Dissipation	$V_I = 12$ V, max $I_O$		2.4		W
$P_{ii}$	Input idling power	$I_O = 0$ , $V_I = 12$ V		560		mW
$P_{inh}$	Input standby power	$V_I = 12$ V (turned off with INHIBIT)		120		mW
$I_s$	Static Input current	$V_I = 12$ V, max $I_O$		TBD		A
$f_s$	Switching frequency	0-100 % of max $I_O$		250		kHz

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}\text{C}$ , $V_I = 12$ V, max $I_O$	1.764	1.800	1.836	V
$V_O$	Output voltage tolerance band	10-100 % of max $I_O$	1.746		1.854	V
	Idling voltage	$I_O = 0$ , $V_I = 12$ V		1.803		V
	Line regulation	max $I_O$		$\pm 10$		mV
	Load regulation	$V_I = 12$ V, 0-100 % of max $I_O$		$\pm 12$		mV
$V_{tr}$	Load transient voltage deviation	$V_I = 12$ V, Load step 50-100-50 % of max $I_O$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		100		mV
$t_{tr}$	Load transient recovery time	$V_I = 12$ V, Load step 50-100-50 % of max $I_O$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		70		$\mu\text{s}$
$t_r$	Ramp-up time (from 10–90 % of $V_O$ )	$V_I = 12$ V, max $I_O$		TBD		ms
$t_s$	Start-up time (from $V_I$ connection to 90 % of $V_O$ )	$V_I = 12$ V, max $I_O$		TBD		ms
$t_f$	Ramp-down time (from 90–10 % of $V_O$ )	Max $I_O$		TBD		$\mu\text{s}$
		$I_O = 0.1$ A		TBD		ms
		$I_O = 0.1$ A		TBD		ms
$T_{inh}$	INHIBIT start-up time	$V_I = 12$ V, Max $I_O$		TBD		ms
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_O$ )	Max $I_O$		TBD		$\mu\text{s}$
		$I_O = 0.1$ A		TBD		ms
		$I_O = 0.1$ A		TBD		ms
$I_O$	Output current		0		8	A
$I_{lim}$	Current limit threshold	$T_{ref} < \text{max } T_{ref}$		16		A
$V_{Oac}$	Output ripple & noise	See ripple & noise section, max $I_O$ , $V_{oi}$		15		mVp-p

Note 1: Output filter according to Ripple &amp; Noise section

PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

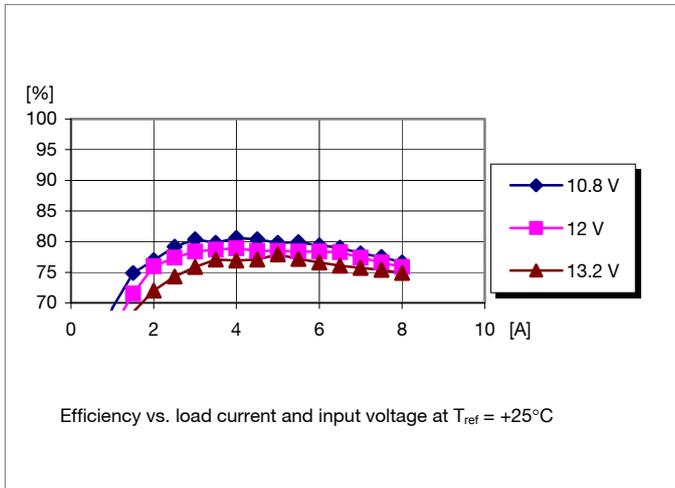
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

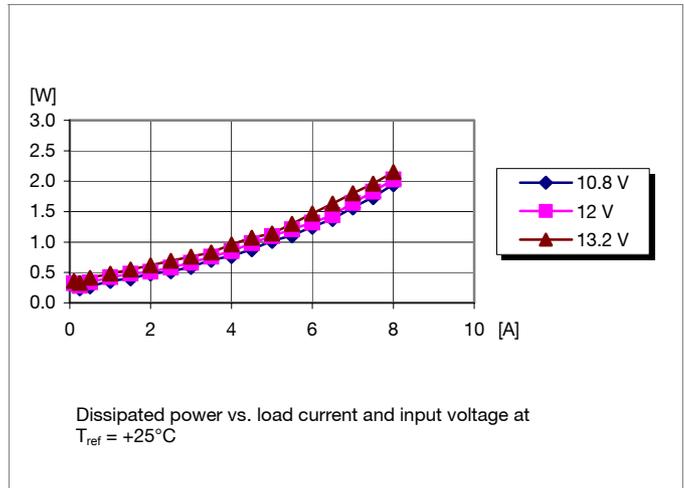
**0.8 V/8 A Typical Characteristics**

**PMK 8118T**

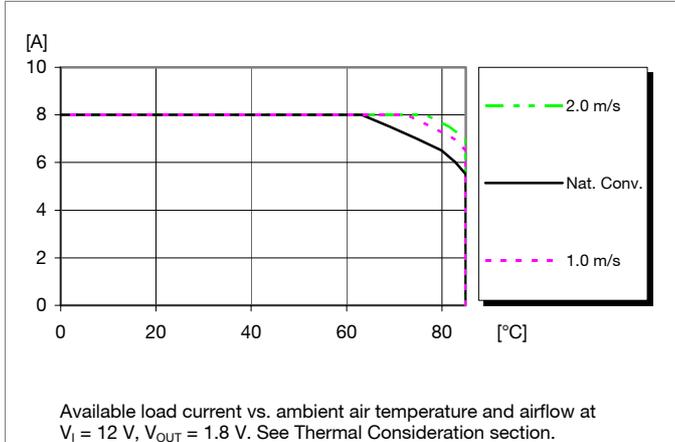
**Efficiency**



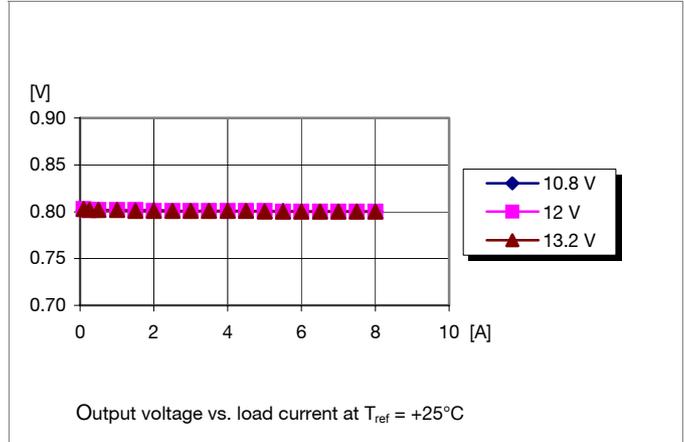
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

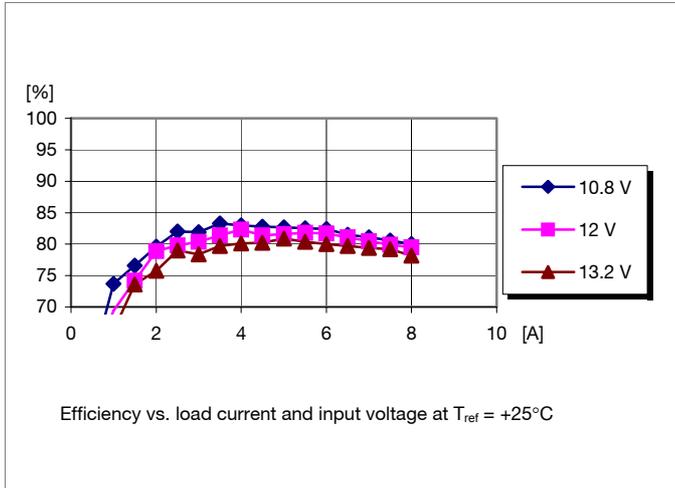
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

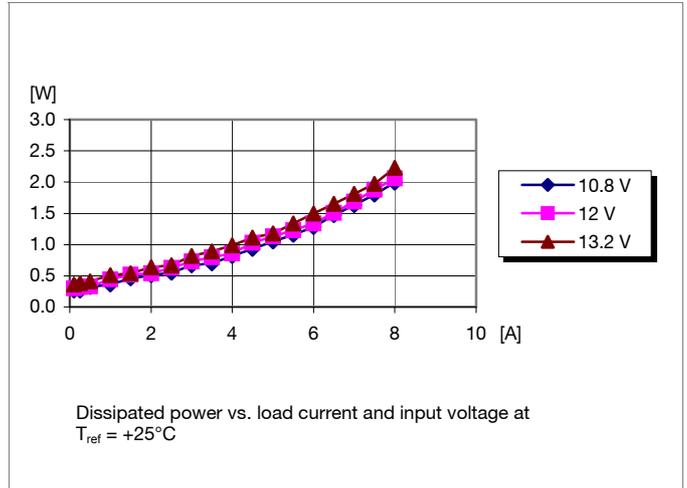
**1.0 V/8 A Typical Characteristics**

**PMK 8118T**

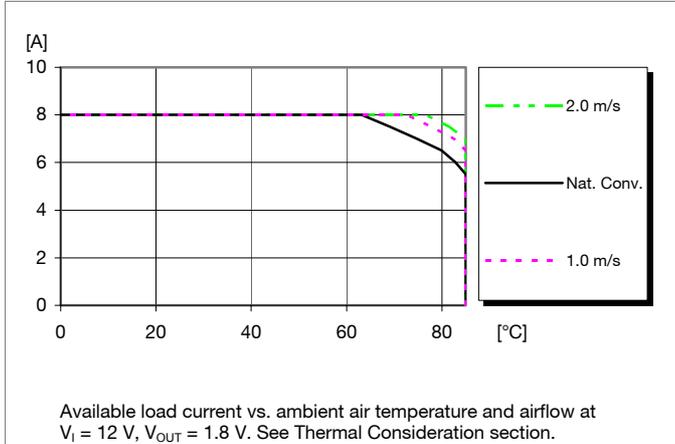
**Efficiency**



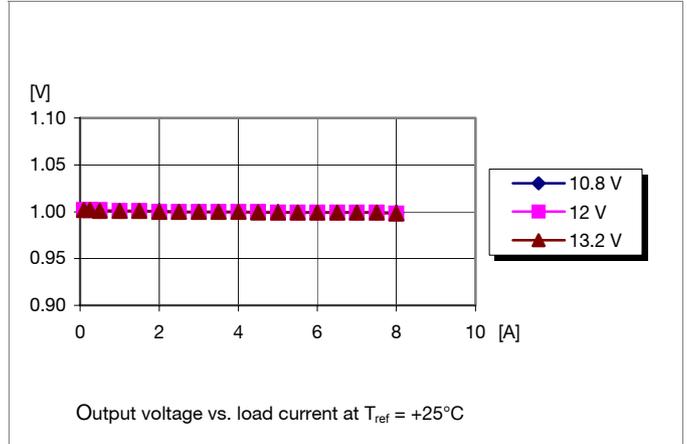
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

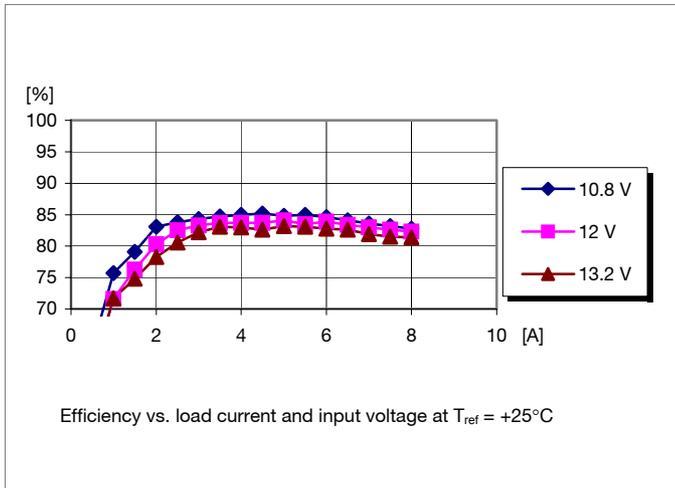
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

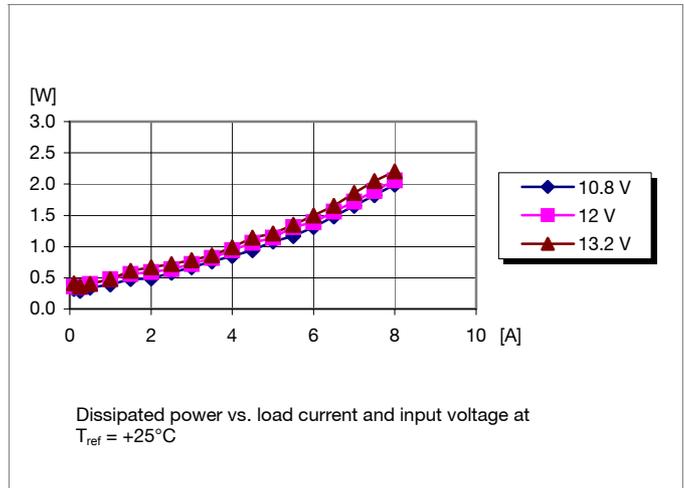
**1.2 V/8 A Typical Characteristics**

**PMK 8118T**

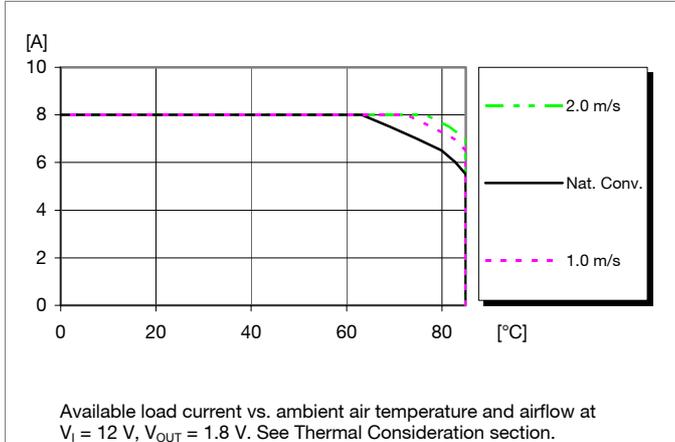
**Efficiency**



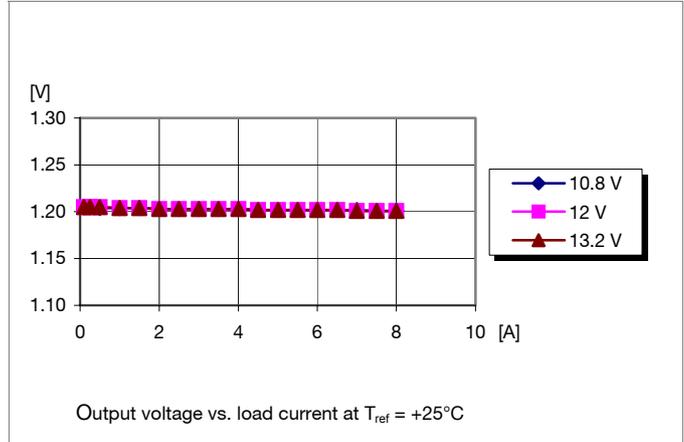
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

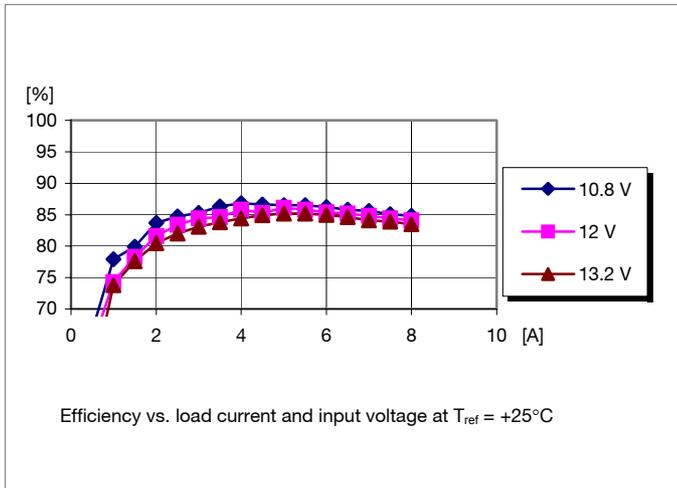
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

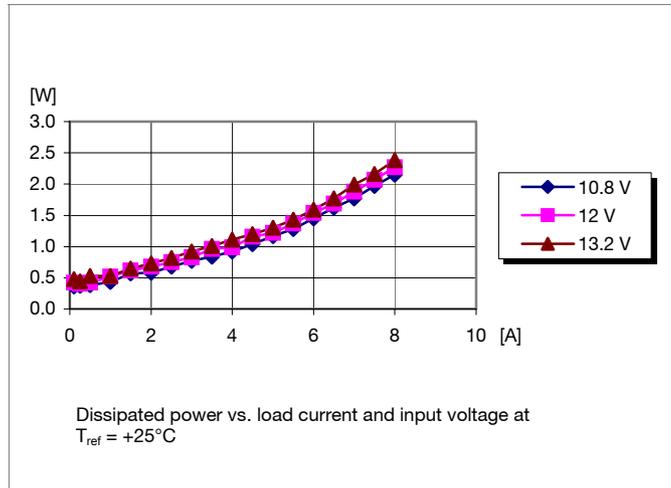
**1.5 V/8 A Typical Characteristics**

**PMK 8118T**

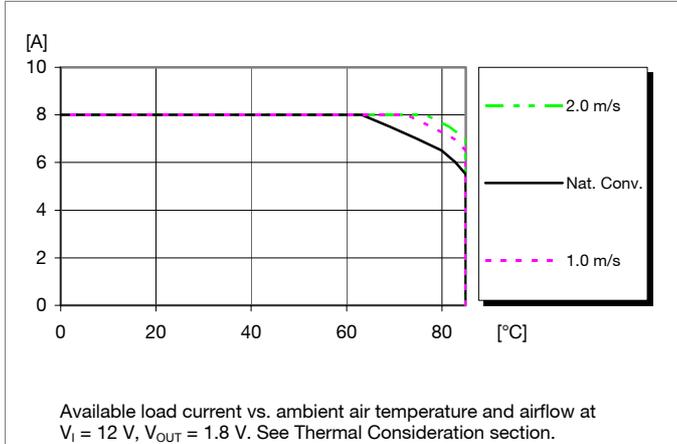
**Efficiency**



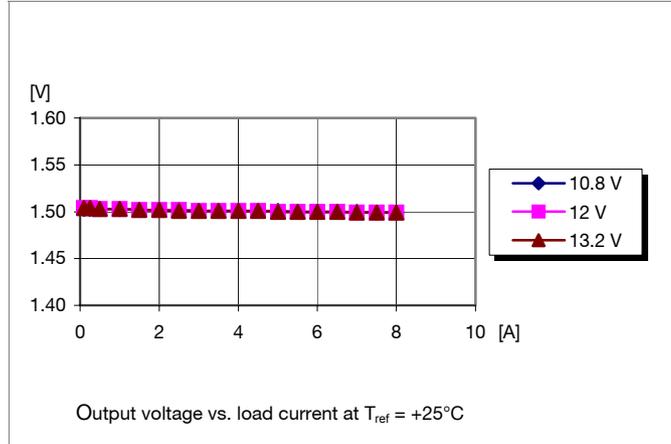
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

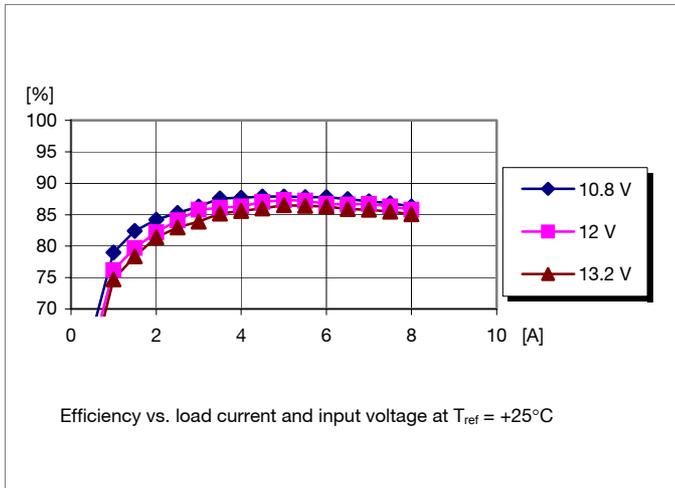
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

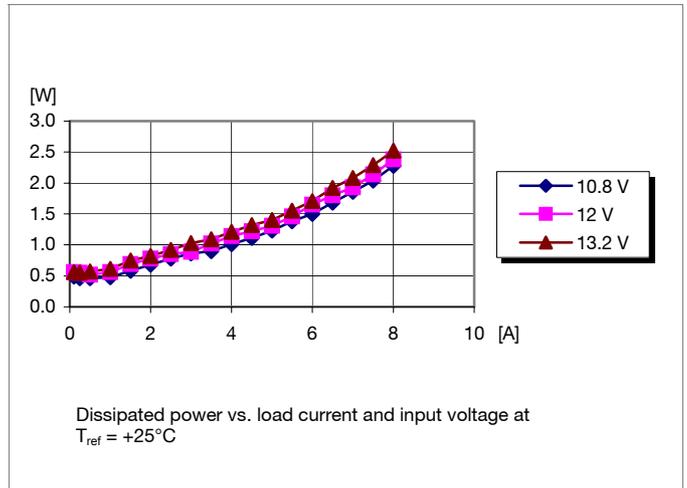
**1.8 V/8 A Typical Characteristics**

**PMK 8118T**

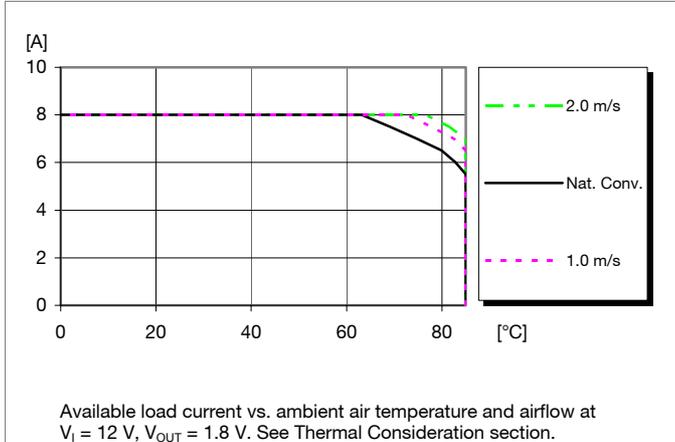
**Efficiency**



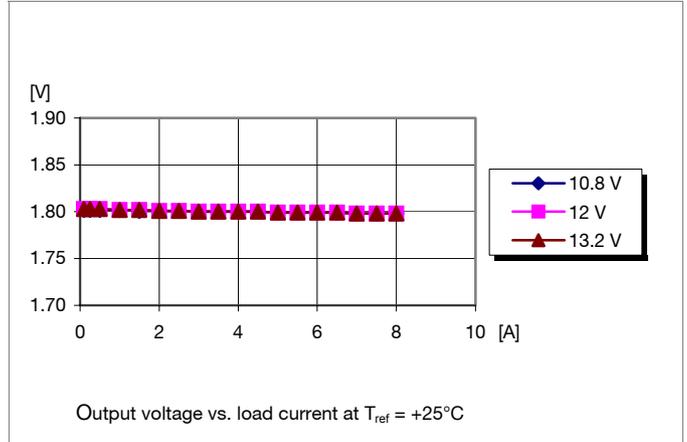
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
 POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

**3.3 V/8 A Electrical Specification**
**PMK 8418L**
 $T_{ref} = -40$  to  $+85^{\circ}\text{C}$ ,  $V_I = 10.8$  to  $13.2$  V,  $R_{adj} = 2$  k $\Omega$ , unless otherwise specified under Conditions.

 Typical values given at:  $T_{ref} = +25^{\circ}\text{C}$ ,  $V_I = 12$  V, max  $I_O$ , unless otherwise specified under Conditions.

 Additional  $C_{in1} = 100\mu\text{F}$ ;  $C_{in2} = 10\mu\text{F}$  and  $C_{out} = 100\mu\text{F}$ . See Operating Information section for selection of capacitor types.

Connect the sense pin, where available, to the output pin.

Characteristics		Conditions	min	typ	max	Unit
$V_I$	Input voltage range		10.8		13.2	V
UVLO	Undervoltage lockout	$V_I = \text{increasing}$		9.5	10.4	V
		$V_I = \text{decreasing}$	8.8	9		
$C_I$	Internal input capacitance			TBD		$\mu\text{F}$
$P_O$	Output power		0		26.4	W
$\eta$	Efficiency	50 % of max $I_O$		TBD		%
		max $I_O$		90		
$P_d$	Power Dissipation	$V_I = 12$ V, max $I_O$		2.9		W
$P_{ii}$	Input idling power	$I_O = 0$ , $V_I = 12$ V		840		mW
$P_{inh}$	Input standby power	$V_I = 12$ V (turned off with INHIBIT)		120		mW
$I_S$	Static Input current	$V_I = 12$ V, max $I_O$		TBD		A
$f_s$	Switching frequency	0-100 % of max $I_O$		325		kHz

$V_{oi}$	Output voltage initial setting and accuracy	$T_{ref} = +25^{\circ}\text{C}$ , $V_I = 12$ V, max $I_O$	3.234	3.300	3.366	V
$V_O$	Output voltage tolerance band	10-100 % of max $I_O$	3.201		3.399	V
	Idling voltage	$I_O = 0$ , $V_I = 12$ V		3.305		V
	Line regulation	max $I_O$		$\pm 10$		mV
	Load regulation	$V_I = 12$ V, 0-100 % of max $I_O$		$\pm 12$		mV
$V_{tr}$	Load transient voltage deviation	$V_I = 12$ V, Load step 50-100-50 % of max $I_O$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		100		mV
$t_{tr}$	Load transient recovery time	$V_I = 12$ V, Load step 50-100-50 % of max $I_O$ , $di/dt = 1$ A/ $\mu\text{s}$ , see Note 1		70		$\mu\text{s}$
$t_r$	Ramp-up time (from 10–90 % of $V_O$ )	$V_I = 12$ V, max $I_O$		TBD		ms
$t_s$	Start-up time (from $V_I$ connection to 90 % of $V_O$ )	$V_I = 12$ V, max $I_O$		TBD		ms
$t_f$	Ramp-down time (from 90–10 % of $V_O$ )	Max $I_O$		TBD		$\mu\text{s}$
		$I_O = 0.1$ A		TBD		ms
		$I_O = 0.1$ A		TBD		ms
$T_{inh}$	INHIBIT start-up time	$V_I = 12$ V, Max $I_O$		TBD		ms
	INHIBIT shutdown fall time (From INHIBIT off to 10 % of $V_O$ )	Max $I_O$		TBD		$\mu\text{s}$
		$I_O = 0.1$ A		TBD		ms
		$I_O = 0.1$ A		TBD		ms
$I_O$	Output current		0		8	A
$I_{lim}$	Current limit threshold	$T_{ref} < \text{max } T_{ref}$		16		A
$V_{Oac}$	Output ripple & noise	See ripple & noise section, max $I_O$ , $V_{oi}$		20		mVp-p

Note 1: Output filter according to Ripple &amp; Noise section

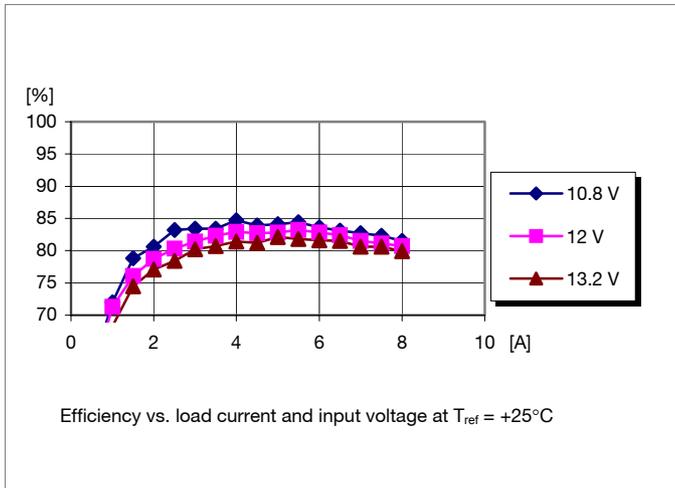
PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

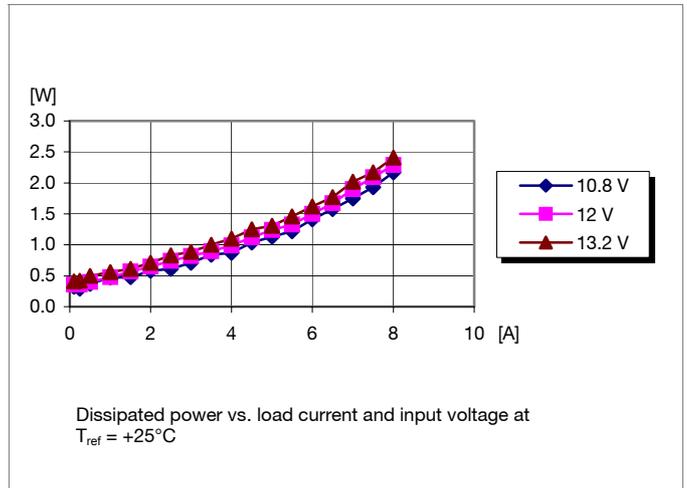
**1.2 V/8 A Typical Characteristics**

**PMK 8418L**

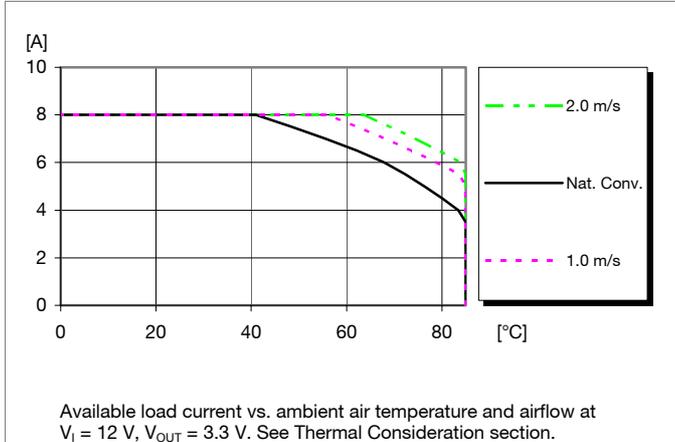
**Efficiency**



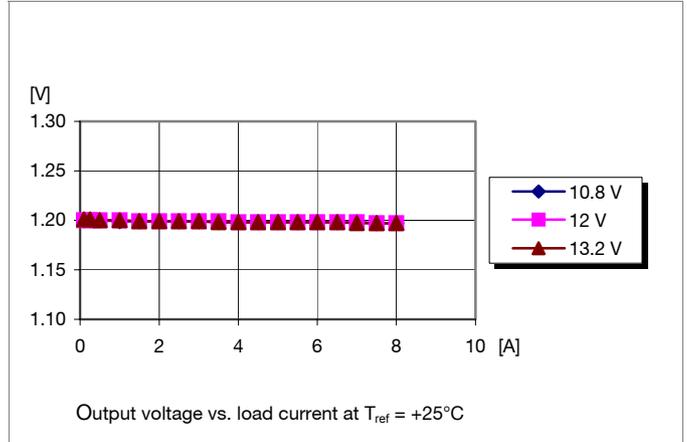
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



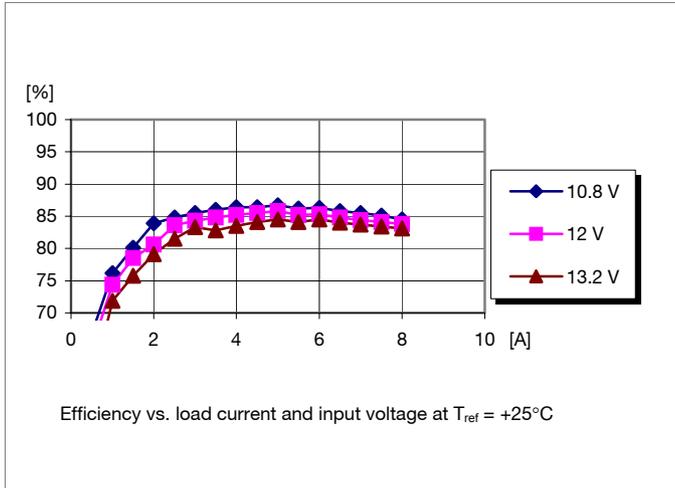
PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

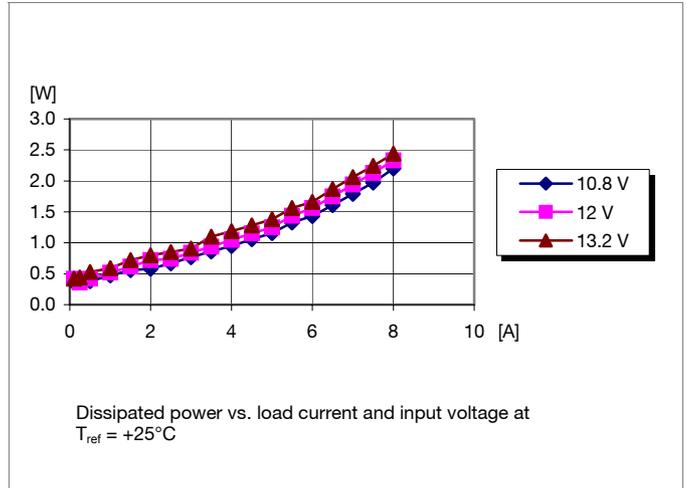
**1.5 V/8 A Typical Characteristics**

**PMK 8418L**

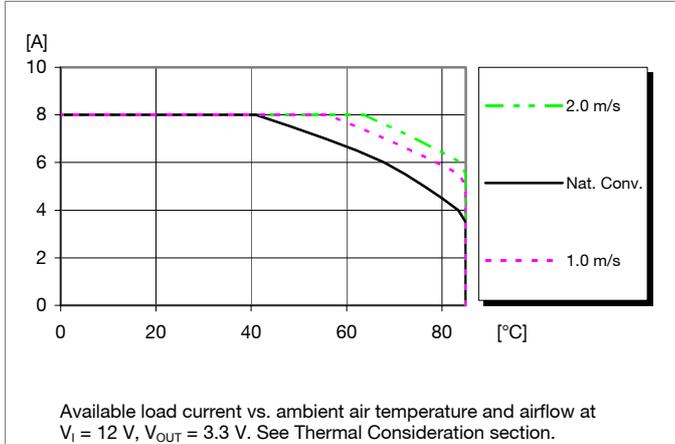
**Efficiency**



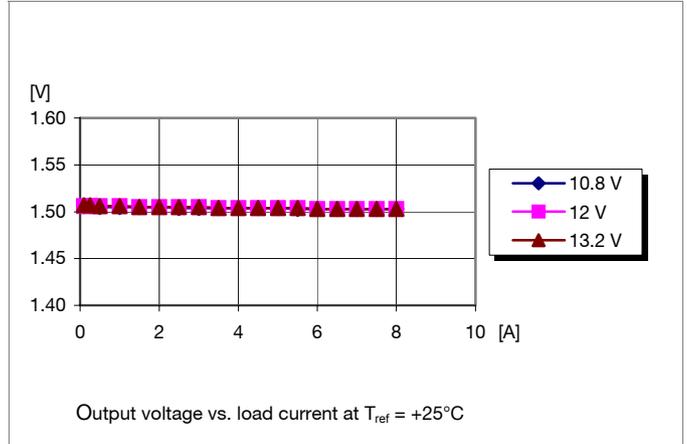
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



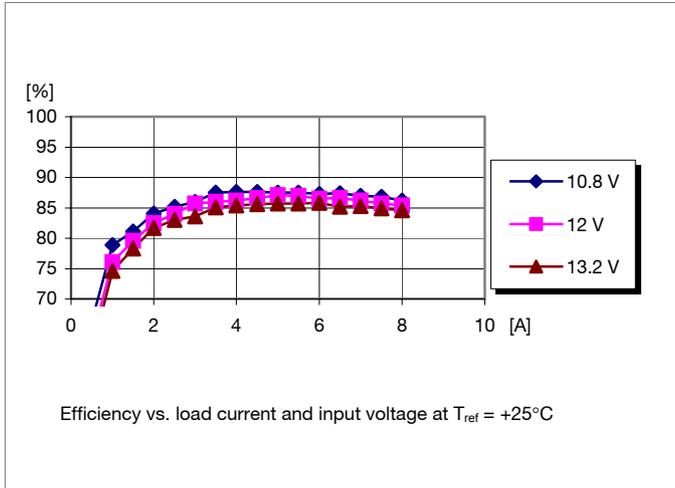
PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

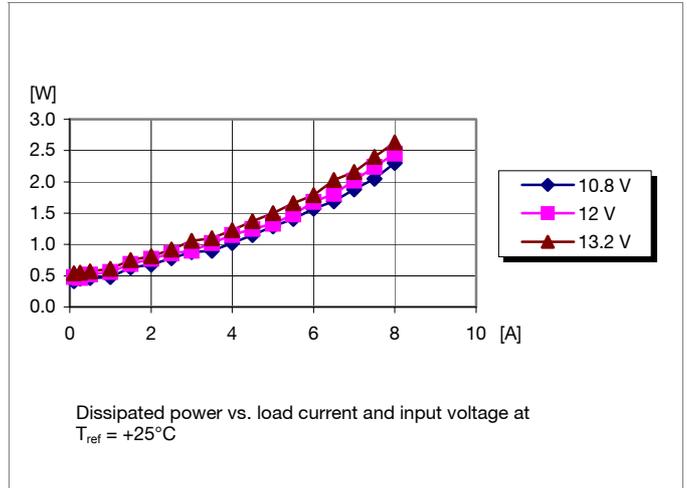
**1.8 V/8 A Typical Characteristics**

**PMK 8418L**

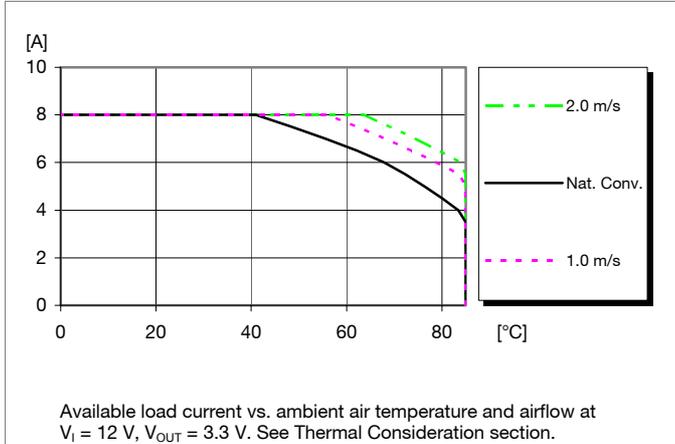
**Efficiency**



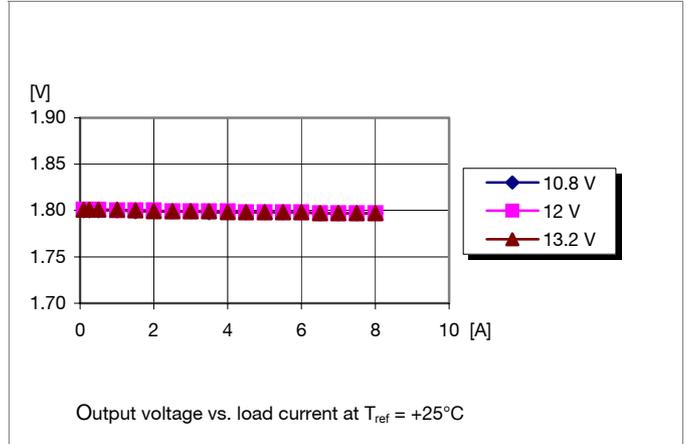
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



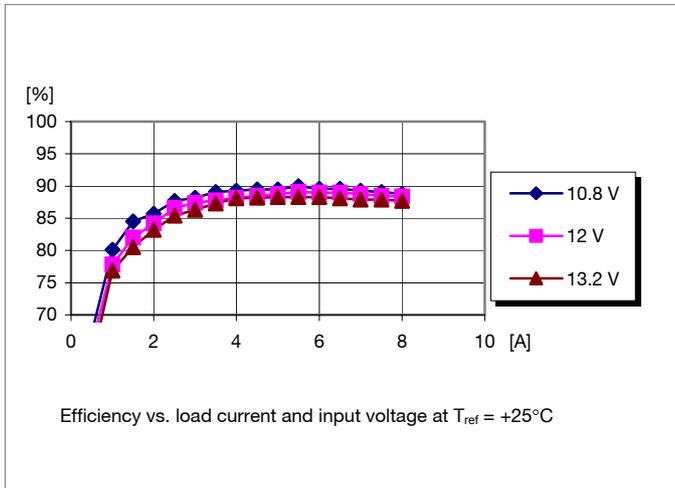
PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

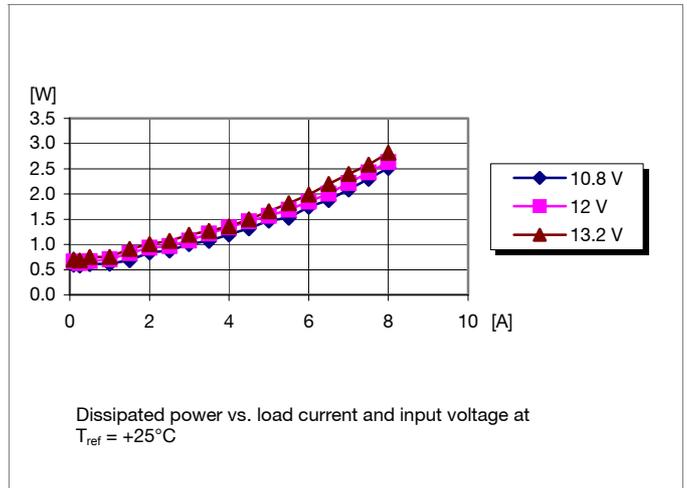
**2.5 V/8 A Typical Characteristics**

**PMK 8418L**

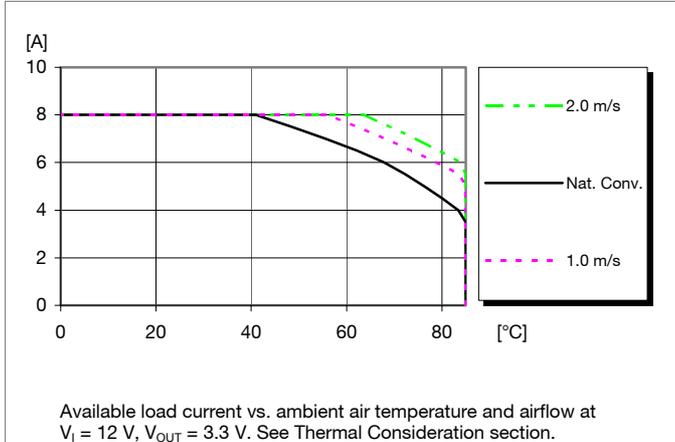
**Efficiency**



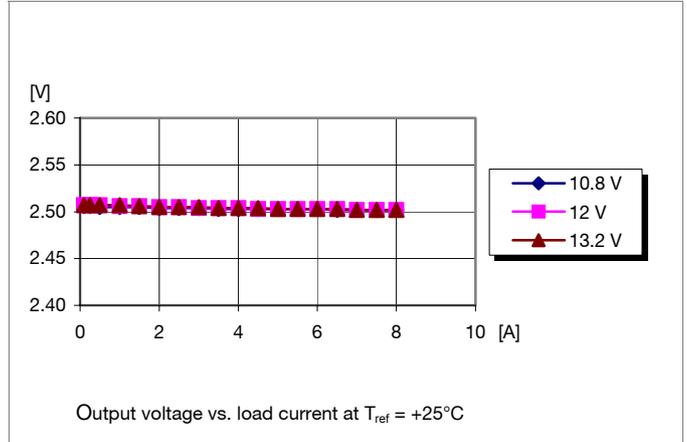
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



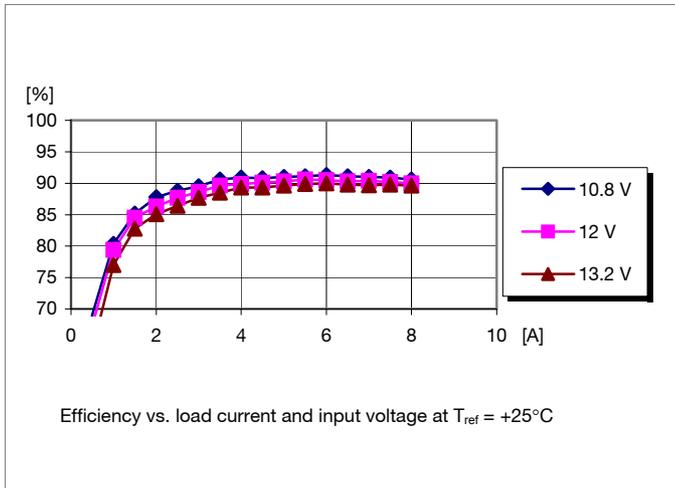
PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

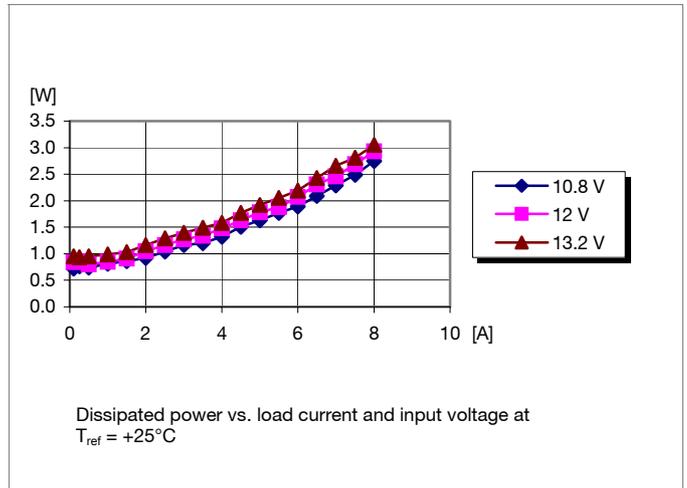
**3.3 V/8 A Typical Characteristics**

**PMK 8418L**

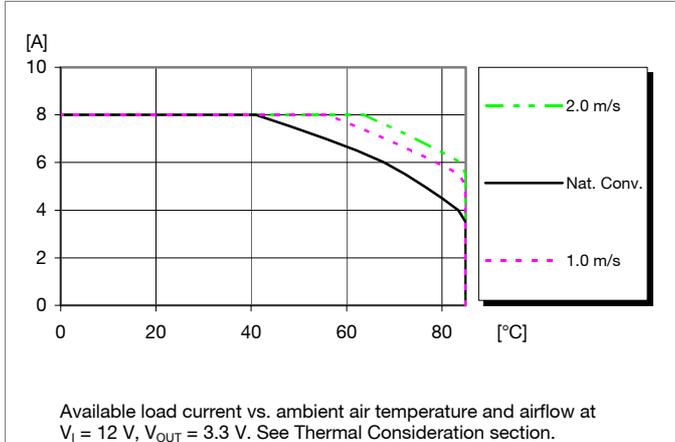
**Efficiency**



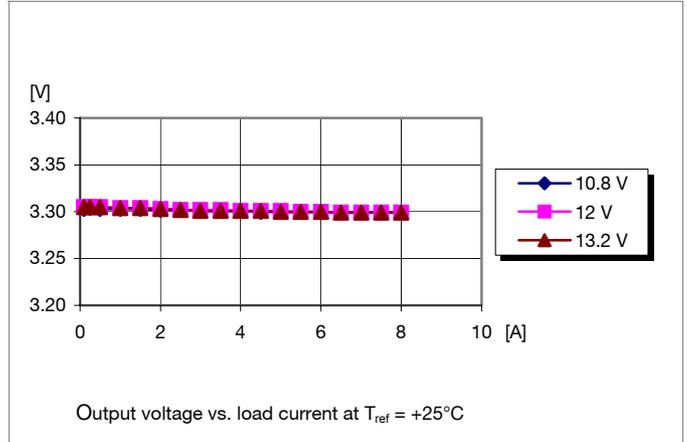
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

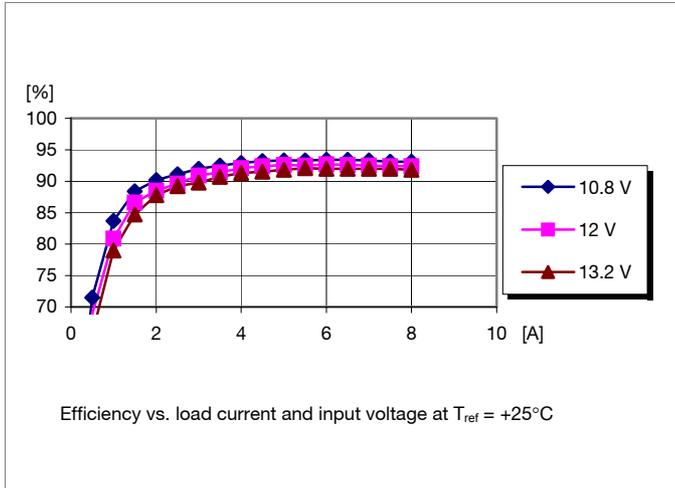
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

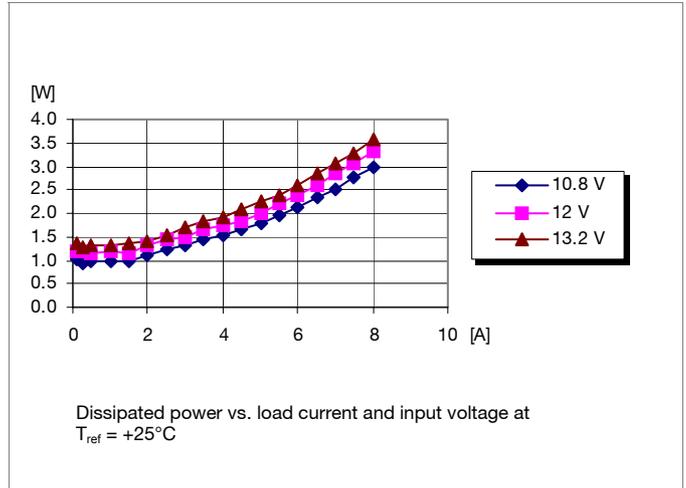
**5.0 V/8 A Typical Characteristics**

**PMK 8418L**

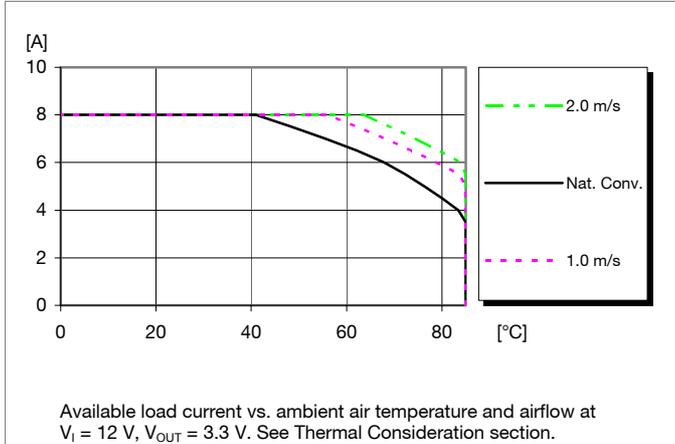
**Efficiency**



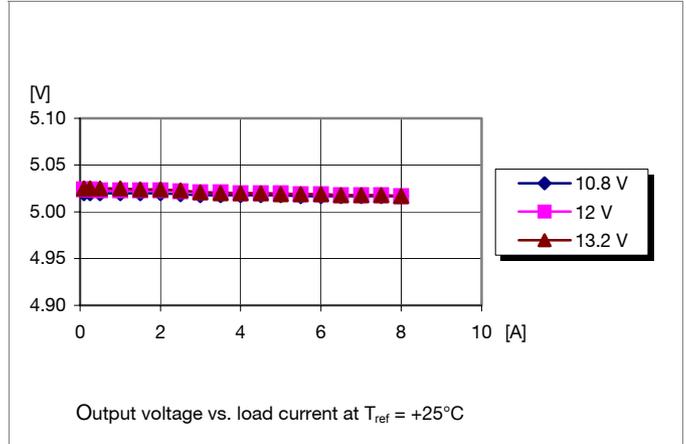
**Power Dissipation**



**Output Current Derating**



**Output Characteristics**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

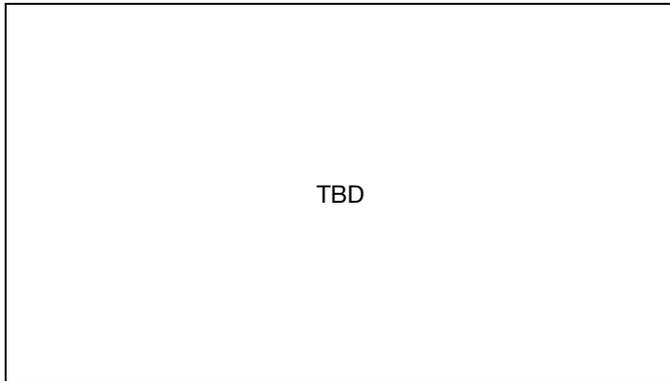
EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

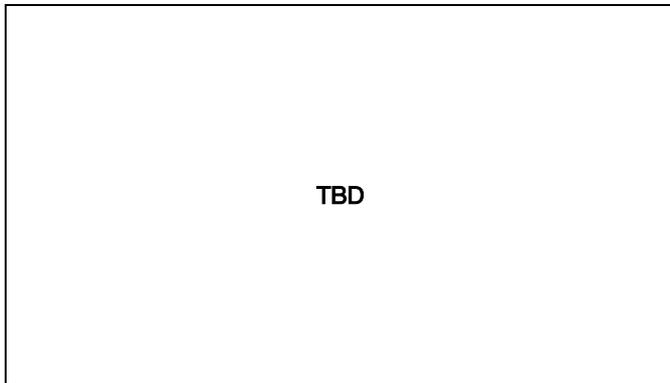
**EMC Specification**

Conducted EMI measured according to test set-up.  
The fundamental switching frequency is 250 kHz for PMK 8118T @  $V_I = 12\text{ V}$ , max  $I_O$  and 325 kHz for PMK 8418L @  $V_I = 12\text{ V}$ , max  $I_O$ .

**Conducted EMI Input terminal value (typ)**



*EMI without filter*



*Test set-up*

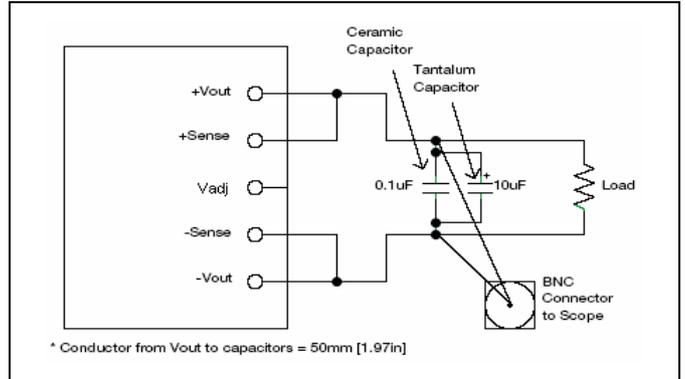
**Layout recommendation**

The radiated EMI performance of the POL regulator will depend on the PCB layout and ground layer design. It is also important to consider the stand-off of the POL regulator.  
If a ground layer is used, it should be connected to the output of the POL regulator and the equipment ground or chassis.

A ground layer will increase the stray capacitance in the PCB and improve the high frequency EMC performance.

**Output ripple and noise**

Output ripple and noise measured according to figure below. See Design Note 022 for detailed information.



*Output ripple and noise test setup*

**Operating information**

Extended information for POLA products is found in Application Note POLA (AN205).

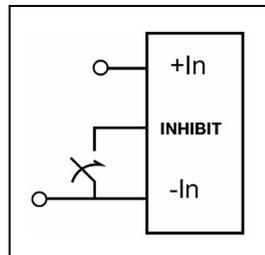
**Input Voltage**

The input voltage range 10.8 to 13.2 Vdc makes the product easy to use in intermediate bus applications when powered by a regulated 12 V bus converter. The PMK product family is also available with 3.3 V or 5  $V_{in}$ .

**Turn on/off Input Voltage**

The POL regulators monitor the input voltage and will turn on and turn off at predetermined levels. The typical hysteresis between turn on and turn off input voltage is 0.5 V.

**Inhibit Control (INH)**



The products are equipped with a Inhibit control function referenced to the primary negative input connection (- In), positive logic. The INHIBIT function allows the regulator to be turned on/off by an external device like a semiconductor or mechanical switch.

The regulator will turn on when the input voltage is applied with the INHIBIT pin open. Turn off is achieved by connecting the INHIBIT pin to the - In. To ensure safe turn off, the voltage difference between INHIBIT pin and the - In pin shall be less than 0.6 V. The regulator will restart automatically when this connection is opened.

PMK 8000 series POL regulator, Input 12 V, Output 8 A/44 W	EN/LZT 146 363 R1B Dec 2006 © Ericsson Power Modules AB
---	--

### External Capacitors

Input capacitors:

The recommended input capacitors are a 10  $\mu\text{F}$  ceramic and a minimum of 100  $\mu\text{F}$  electrolytic type. The 100  $\mu\text{F}$  capacitance must be rated for 700 mArms ripple current capability. For  $V_o \leq 3 \text{ V}$ , the ripple current rating must be at least 450 mArms.

Output capacitors (optional):

The recommended output capacitance of 100  $\mu\text{F}$  will allow the module to meet its transient response specification as defined in the electrical specification.

When using one or more non-ceramic capacitors, the calculated equivalent ESR should be no lower than 4 m $\Omega$  (7m $\Omega$  using the manufacturer's maximum ESR for a single capacitor).

### Input And Output Impedance

The impedance of both the input source and the load will interact with the impedance of the POL regulator. It is important that the input source has low characteristic impedance. The regulators are designed for stable operation without external capacitors connected to the input or output. The performance in some applications can be enhanced by addition of external capacitance as described under External Decoupling Capacitors. If the input voltage source contains significant inductance, the addition of a 100  $\mu\text{F}$  capacitor across the input of the POL regulator will ensure stable operation. The capacitor is not required when powering the POL regulator from an input source with an inductance below 10  $\mu\text{H}$ .

### External Decoupling Capacitors

When powering loads with significant dynamic current requirements, the voltage regulation at the point of load can be improved by addition of decoupling capacitors at the load. The most effective technique is to locate low ESR ceramic and electrolytic capacitors as close to the load as possible, using several parallel capacitors to lower the effective ESR. The ceramic capacitors will handle high-frequency dynamic load changes while the electrolytic capacitors are used to handle low frequency dynamic load changes. Ceramic capacitors will also reduce any high frequency noise at the load.

It is equally important to use low resistance and low inductance PCB layouts and cabling.

External decoupling capacitors will become part of the control loop of the POL regulator and may affect the stability margins. As a "rule of thumb", 100  $\mu\text{F}/\text{A}$  of output current can be added without any additional analysis. The ESR of the capacitors is a very important parameter. Power Modules guarantee stable operation with a verified ESR value of >10 m $\Omega$  across the output connections.

For further information please contact your local Ericsson Power Modules representative.

### Output Voltage Adjust ( $V_{\text{adj}}$ )

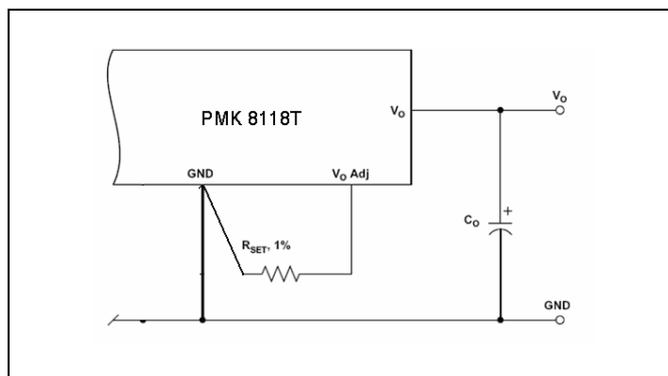
The output voltage can be set by means of an external resistor, connected to the  $V_{\text{adj}}$  pin. Nominal output voltage 0.8 V(for PMK 8118T) and 1.2 V(for PMK 8418L) is set by leaving the  $V_{\text{adj}}$  pin open. Adjustment can only be made to increase the output voltage setting.

To increase the voltage a resistor should be connected between the  $V_{\text{adj}}$  pin and GND pin. The resistor value of the Output voltage adjust function can be calculated according to the following formula.

$$R_{\text{SET}} = 10 \text{ k}\Omega \times 0.8 \text{ V} / (V_o - V_{\text{min}}) - R_s \text{ k}\Omega$$

For PMK 8118T:  $V_{\text{min}} = 0.8 \text{ V}$ ;  $R_s = 7.87 \text{ k}\Omega$

For PMK 8418L:  $V_{\text{min}} = 1.2 \text{ V}$ ;  $R_s = 1.82 \text{ k}\Omega$



### Parallel Operation

Two POL regulators may be paralleled for redundancy if the total power is equal or less than  $P_o$  max. It is not recommended to parallel the POL regulators without using external current sharing circuits.

### Over Current Protection (OCP)

The POL regulators include current limiting circuitry for protection at continuous overload.

The output voltage will decrease towards zero for output currents in excess of the over-current threshold. The regulator will resume normal operation after removal of the overload. The load distribution should be designed for the maximum output short circuit current specified. The current limit operation is a "hick up" mode current limit.

### Soft-start Power Up

From the moment a valid input voltage is applied, the soft-start control introduces a short time-delay (typically 8 ms to 15 ms) before allowing the output voltage to rise. The initial rise in input current when the input voltage first starts to rise is the charge current drawn by the input capacitors. Power-up is complete within 25 ms.

PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

**Auto-Track™ Function**

The AutoTrack function is designed so that 2 or more POL regulators can track each others output voltage tightly together. This can be accomplished by connection the AutoTrack pin to the output of another POL regulator or by feeding an external voltage ramp on the pin. The AutoTrack will automatically track any external voltage that is applied within the given rules in Application Note POLA (AN205).

**Pre-Bias Startup Capability**

This often occurs in complex digital systems when current from another power source is backfed through a dual-supply logic component, such as FPGA or ASIC. The PMK family products incorporate synchronous rectifiers, but will not sink current during startup, or whenever the Inhibit pin is held low. However, to ensure satisfactory operation of this function, certain conditions must be maintained.

**Thermal Consideration**

**General**

The POL regulators are designed to operate in different thermal environments and sufficient cooling must be provided to ensure reliable operation. Cooling is achieved mainly by conduction, from the pins to the host board, and convection, which is dependant on the airflow across the regulator. Increased airflow enhances the cooling of the POL regulator.

The Output Current Derating graph found in the Output section for each model provides the available output current vs. ambient air temperature and air velocity at  $V_{in} = 12 V$ .

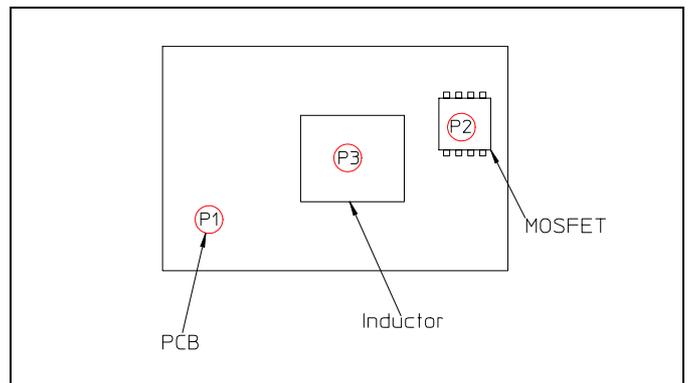
The POL regulator is tested on a 254 x 254 mm, 35  $\mu m$  (1 oz), 8-layer test board mounted vertically in a wind tunnel with a cross-section of 305 x 305 mm.

Proper cooling of the POL regulator can be verified by measuring the temperature at positions P1, P2 and P3. The temperature at these positions should not exceed the max values provided in the table below.

Note that the max value is the absolute maximum rating (non destruction) and that the electrical Output data is guaranteed up to  $T_{amb} + 85^{\circ}C$ .

See Design Note 019 for further information.

Position	Device	Designation	max value
P <sub>1</sub>	Pcb		130° C(L&T)
P <sub>2</sub>	Mosfet	T <sub>ref</sub>	130° C(L&T)
P <sub>3</sub>	Inductor		130° C(L&T)



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

### Thermal Consideration continued

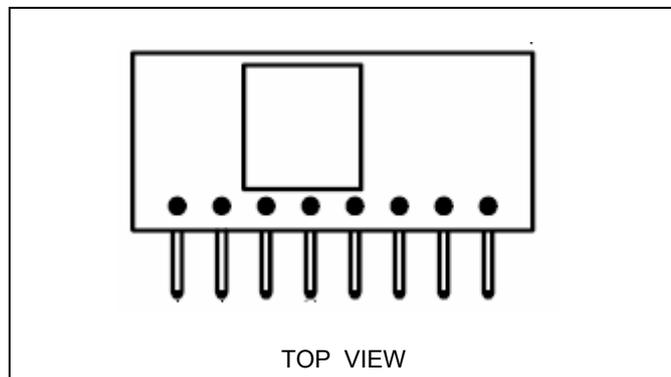
#### Definition of reference temperature ( $T_{ref}$ )

The reference temperature is used to monitor the temperature limits of the product. Temperatures above maximum  $T_{ref}$  are not allowed and may cause degradation or permanent damage to the product.  $T_{ref}$  is also used to define the temperature range for normal operating conditions.  $T_{ref}$  is defined by the design and used to guarantee safety margins, proper operation and high reliability of the module.

#### Ambient Temperature Calculation

TBD

### Connections

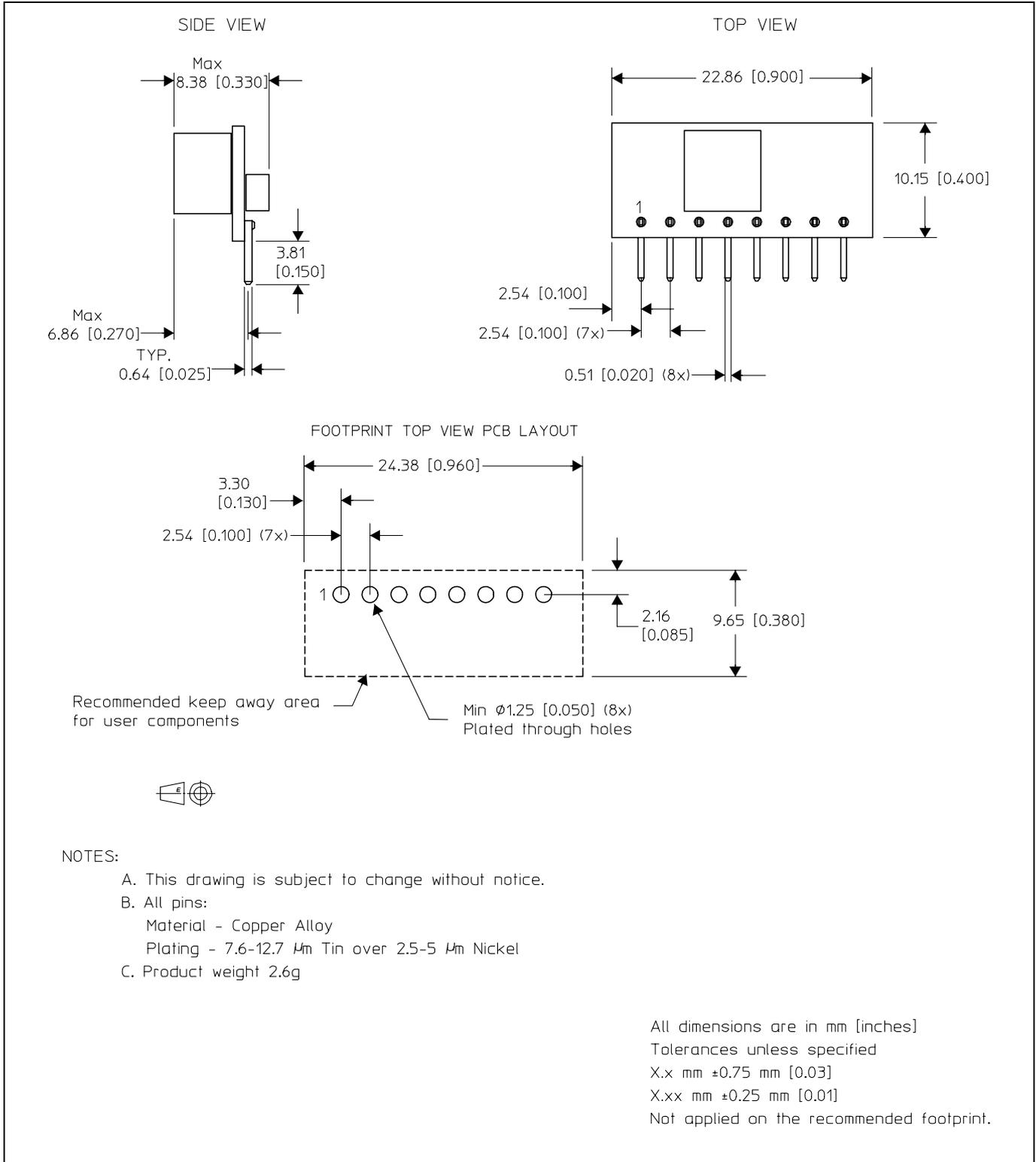


Pin	Designation	Function
1,6	GND	Common ground connection for the $V_{in}$ and $V_{out}$ power connections.
2,3	$V_{out}$	The regulated positive power output with respect to the GND node.
4	$V_o$ Adjust	A 0.1 W 1% resistor must be directly connected between this pin and pin 1(GND) to set the output voltage.
5	Track	This is an analog control input that enables the output voltage to follow an external voltage.
7	Inhibit	Applying a low-level ground signal to this input disables the module's output.
8	$V_{in}$	The positive input voltage power node to the module.

PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006  
© Ericsson Power Modules AB

**Mechanical Information**



PMK 8000 series  
POL regulator, Input 12 V, Output 8 A/44 W

EN/LZT 146 363 R1B Dec 2006

© Ericsson Power Modules AB

### Soldering Information – Through Hole Mounting

The through hole mount version of the product is intended for through hole mounting in a PCB. When wave soldering is used, the temperature on the pins is specified to maximum 270 °C for maximum 10 seconds.

Maximum preheat rate of 4 °C/s and temperature of max 150 °C is suggested. When hand soldering, care should be taken to avoid direct contact between the hot soldering iron tip and the pins for more than a few seconds in order to prevent overheating.

A no-clean (NC) flux is recommended to avoid entrapment of cleaning fluids in cavities inside of the DC/DC power module. The residues may affect long time reliability and isolation voltage.

### Delivery package information

The products can be delivered in antistatic trays.

Tray specifications	
<b>Material</b>	PET
<b>Surface resistance</b>	$10^5 < \text{ohms/square} < 10^{12}$
<b>Bake ability</b>	The trays can not be baked.
<b>Tray capacity</b>	70 products /tray
<b>Box capacity</b>	350 products/box

PMK 8000 series POL regulator, Input 12 V, Output 8 A/44 W	EN/LZT 146 363 R1B Dec 2006
	© Ericsson Power Modules AB

**Product Qualification Specification**

Characteristics			
Visual inspection	IPC-A-610		
Biased life	MIL-STD-202F Method 108	Temperature Airflow Duration	Ambient temperature Convection airflow 1000 hours
Biased humidity	MIL-STD-202F Method 103	Temperature Humidity Duration	+85 °C 85 % RH 1000 hours
Thermal shock	MIL-STD-202F Method 107	Dwell time Temperature Number of cycles	15 min at each temperature extreme -40 °C to +125 °C 200 cycles
Sinusoidal vibration	MIL-STD-883D Method 2007.2	Frequency Duration  Number of shocks	20 – 2000 Hz 4 minutes in each direction (+/-) of three axes 4 in each direction (+/-) of three axes
Mechanical shock	MIL-STD-883D Method 2002.3	Peak acceleration Half-sine duration Number of shocks	500 g 1 ms 5 in each direction (+/-) of three axes
Radiated emissions	EN55022	Class B	
Conducted emissions	EN55022		